

DYNAMIC SPANNER basic

- 2) general intro to static spanner

- 1) general intro to expanders & expander decomps

0) THM

1) properties of our static spanner

2) use patching & batching of ^{static} spanner to build
dynamic spanner

A) lengths & recourse

B) running time \rightarrow vertex congestion

3) more about the static spanner

Stretch of an edge w.r.t. a subgraph

$G = (V, E)$, subgraph $H = (V, F)$ $F \subseteq E$

$\text{str}_H(e) = \text{length of } \overset{\text{embedding path}}{\text{shortest path}} \text{ in } H$
from u to v

Baswana-Seq '03

THM Graph $G = (V, E)$ n vertices
 m edges

There exists a subgraph $H = (V, F)$
 $F \subseteq E$

$$|F| \leq \tilde{O}(n)$$

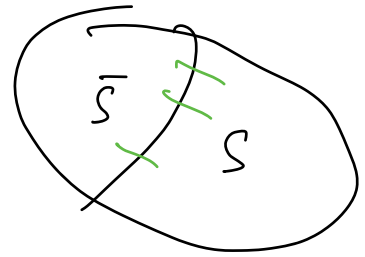
with $\forall e \in E$ $\text{str}_H(e) \leq \tilde{O}(1)$

- compute in time $\tilde{O}(m)$

DEFN $G = (V, E)$ is φ -expander iff

For all $S \subseteq V$

$$\frac{|E(S, \bar{S})|}{\min(\text{vol}(S), \text{vol}(\bar{S}))} \geq \varphi$$



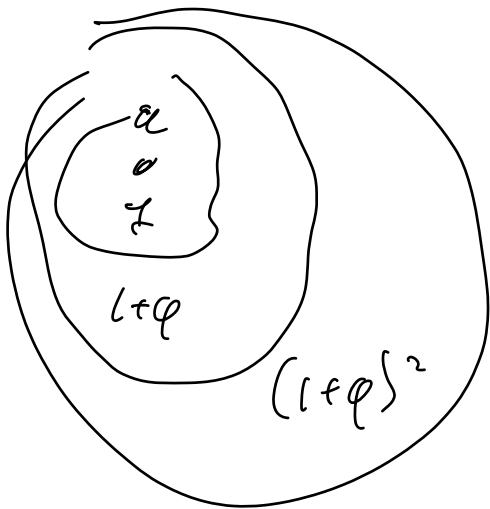
$$\text{vol}(S) = \sum_{v \in S} \text{deg}(v)$$

CLAIM

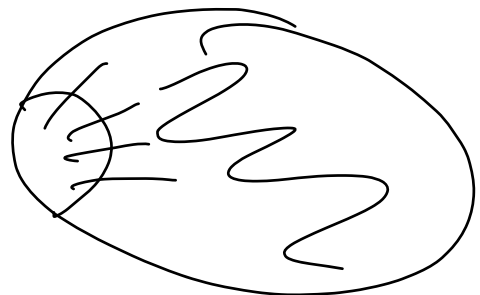
G φ -expander

\Downarrow

$$\text{diam}(G) \leq O\left(\frac{1}{\varphi}\right)$$



or



$$t = \frac{L_{\max}}{\varphi}$$

$$(1 + \varphi)^t$$

CLAIM Suppose G is a q -expander
w. min degree d

Make H by indep. sampling each edge
of G w. prob $\tilde{O}\left(\frac{1}{d \cdot q}\right)$

Then whp. H is a $q/2$ expander ~~$\tilde{O}(d)$~~
and has $\tilde{O}\left(\frac{n}{dq}\right)$ edges.

Corollary: if the avg. deg. in G is $\tilde{O}(d)$
then H has $\tilde{O}\left(\frac{n}{q}\right)$ edges

$$\frac{n \cdot d_{\text{avg}}}{2} \approx d$$

Coroll. If $\frac{1}{q} = \tilde{O}(1)$ as well
then H is a decent sparser of G

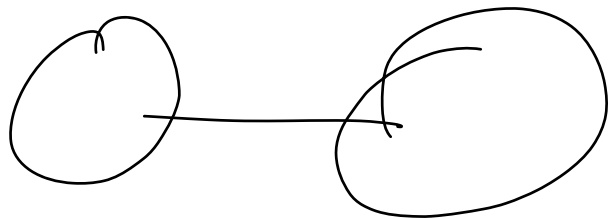
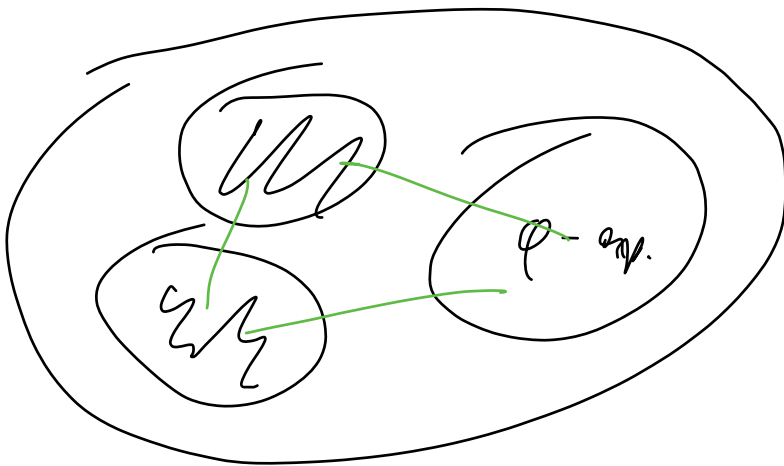
Expander decomp Sarason-Wang '2019

Given $G = (V, E)$ we can partition V into
 V_1, \dots, V_k

s.t. $G[V_j]$ is a φ -expander for all $j \in [k]$
 \downarrow
 $\frac{1}{\alpha(1)} = \tilde{\Omega}(1)$
 $\alpha(1)$

with $\leq \frac{m}{\varphi}$ edges crossing the partition.

The algo runs
in time $O(m)$.



Degree-controlled Exp D. THM

Given G has max deg Δ

then we can partition the edge set

into $1 + \log_2 \Delta$ pieces E_0, \dots, E_ℓ " $\log_2 \Delta$ "

st. For $i > 0$ each conn. component of E_i
is $\tilde{S}(1)$ expander

with min-deg $\underline{\tilde{S}(2^i)}$

and $|E_i| \leq 2^i n^{d_i}$

E_i



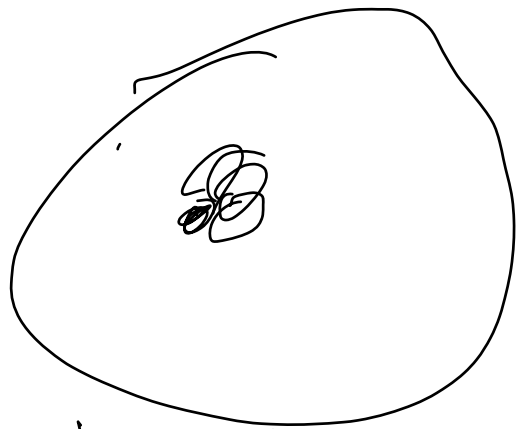
$$|E_0| \leq n$$

Pf sketch $G_{l+1} \leftarrow G$

for $i = l, \dots, 1$

For G_i add 2^i

self loops per vertex to G_{i+1}



Apply E.D. to G_i

C_i : crossing edges of E.D.

verts $v^{(i)}_1 \dots v^{(i)}_n$

$G_i \leftarrow (V, C_i)$

$$\begin{array}{c}
 s \parallel v \in V_f^{(i)} \\
 |E(s, \bar{s})| \\
 \frac{\deg(v)}{\cancel{\deg(v)}} \geq \tilde{\Omega}(1) \\
 \deg(v) + 2^i
 \end{array}$$

\downarrow
 edges internal
 to $E.P.$

$$\begin{array}{cc}
 m_{i+1} \leq \Delta n & 2^i \cdot n \\
 \underline{\quad} & \parallel \\
 & \Delta \\
 2\Delta n &
 \end{array}$$

$$\begin{array}{cc}
 \text{leftover} & \frac{2\Delta n}{4} \\
 & \frac{\Delta n}{2}
 \end{array}$$